

# ELECTRICAL ENGINEERING OPTIONAL SYLLABUS

## PAPER - I

### 1. Circuits—Theory :

Circuit components; network graphs; KCL, KVL; Circuit analysis methods : nodal analysis, mesh analysis; basic network theorems and applications; transient analysis : RL, RC and RLC circuits; sinusoidal steady state analysis; resonant circuits; coupled circuits; balanced 3-phase circuits. Two-port networks.

### 2. Signals and Systems :

Representation of continuous-time and discrete-time signals and systems; LTI systems; convolution; impulse response; time-domain analysis of LTI systems based on convolution and differential/difference equations. Fourier transform, Laplace transform, Z-transform, Transfer function. Sampling and recovery of signals DFT, FFT Processing of analog signals through discrete-time systems.

### 3. E.M. Theory :

Maxwell's equations, wave propagation in bounded media. Boundary conditions, reflection and refraction of plane waves. Transmission lines : travelling and standing waves, impedance matching, Smith chart.

### 4. Analog Electronics :

Characteristics and equivalent circuits (large and small-signal) of Diode, BJT, JFET and MOSFET. Diode circuits : Clipping, clamping, rectifier. Biasing and bias stability. FET amplifiers. Current mirror; Amplifiers : single and multi-stage, differential, operational feedback and power. Analysis of amplifiers; frequency-response of amplifiers. OPAMP circuits. Filters; sinusoidal oscillators : criterion for oscillation; single-transistor and OPAMP configurations. Function generators and wave-shaping circuits. Linear and switching power supplies.

### 5. Digital Electronics :

Boolean algebra; minimisation of Boolean functions; logic gates; digital IC families (DTL, TTL, ECL, MOS, CMOS). Combinational circuits : arithmetic circuits, code converters, multiplexers and decoders. Sequential circuits: latches and flip-flops, counters and shift-registers. Comparators, timers, multivibrators. Sample and hold circuits, ADCs and DACs. Semiconductor memories. Logic implementation using programmable devices (ROM, PLA, FPGA).

## **6. Energy Conversion :**

**Principles of electromechanical energy conversion : Torque and emf in rotating machines. DC machines : characteristics and performance analysis; starting and speed control of motors. Transformers : principles of operation and analysis; regulation, efficiency; 3-phase transformers. 3-phase induction machines and synchronous machines : characteristics and performance analysis; speed control.**

## **7. Power Electronics and Electric Drives :**

**Semi-conductor power devices : diode, transistor, thyristor, triac, GTO and MOSFET-static characteristics and principles of operation; triggering circuits; phase control rectifiers; bridge converters : fully-controlled and half-controlled; principles of thyristor choppers and inverters; DC-DC converters; Switch mode inverter; basic concepts of speed control of dc and ac motor drives applications of variable-speed drives.**

## **8. Analog Communication :**

**Random variables : continuous, discrete; probability, probability functions. Statistical averages; probability models; Random signals and noise : white noise, noise equivalent bandwidth; signal transmission with noise; signal to noise ratio. Linear CW modulation : Amplitude modulation : DSB, DSB-SC and SSB. Modulators and Demodulators; Phase and Frequency modulation : PM & FM signals; narrow band FM; generation & detection of FM and PM, Deemphasis, Preemphasis. CW modulation system : Superhetrodyne receivers, AM receivers, communication receivers, FM receivers, phase locked loop, SSB receiver Signal to noise ratio calculation or AM and FM receivers.**

## PAPER - II

### 1. Control Systems :

Elements of control systems; block-diagram representations; open-loop & closed-loop systems; principles and applications of feed-back. Control system components. LTI systems : time-domain and transform-domain analysis. Stability : Routh Hurwitz criterion, root-loci, Bode-plots and polar plots, Nyquist's criterion; Design of lead-lag compensators. Proportional, PI, PID controllers. State-variable representation and analysis of control systems.

### 2. Microprocessors and Microcomputers :

PC organisation; CPU, instruction set, register setting diagram, programming, interrupts, memory interfacing, I/O interfacing, programmable peripheral devices. 3. Measurement and Instrumentation : Error analysis; measurement of current voltage, power, energy, power-factor, resistance, inductance, capacitance and frequency; bridge measurements. Signal conditioning circuit; Electronic measuring instruments : multimeter, CRO, digital voltmeter, frequency counter, Q-meter, spectrum-analyser, distortion-meter. Transducers : thermocouple, thermistor, LVDT, strain-gauge, piezo-electric crystal.

### 4. Power Systems: Analysis and Control :

Steady-state performance of overhead transmission lines and cables; principles of active and reactive power transfer and distribution; per-unit quantities; bus admittance and impedance matrices; load flow; voltage control and power factor correction; economic operation; symmetrical components, analysis of symmetrical and unsymmetrical faults. Concepts of system stability : swing curves and equal area criterion. Static VAR system. Basic concepts of HVDC transmission.

### 5. Power System Protection :

Principles of overcurrent, differential and distance protection. Concept of solid state relays. Circuit breakers. Computer aided protection : introduction; line, bus, generator, transformer protection; numeric relays and application of DSP to protection.

### 6. Digital Communication :

Pulse code modulation (PCM), differential pulse code modulation (DPCM), delta modulation (DM), Digital modulation and demodulation schemes : amplitude, phase and frequency keying schemes (ASK, PSK, FSK). Error control coding : error detection and correction, linear block codes, convolution codes. Information measure and source coding. Data networks, 7-layer architecture.